

PREDICTION OF CHRONIC BACTERIAL INFECTION BY IDENTIFICATION OF INTERCELLULAR RESPONSES OF GENETIC FUSION CENTERS

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ABSTRACT

Objective: In this study, we have designed an algorithm for early detection of DNA fusion to discover the potential transcription which embodies the fusion of gene products derivable from the human DNA with that of bacterial and cancerous viruses, resulting from the several breakage points and re-assembling of different chromosomes, or that of within a chromosome.

Methods: Without relying on existing annotations, the proposed algorithm proves its efficacy in detecting alignment of RNA sequences from unannotated splice variants of known genome strands. Using this algorithm in the age of Big Data analytics the potential threat of cancer, tuberculosis, tumors, and asthma can be predicted beforehand while scaling such effects, ranging from individual to population scale.

Results and Conclusion: We have also reported the results of the algorithm for over 90 samples with solid supporting evidences and open a new virotherapy approach of a numerically quantized cure for a disease such as cancer, tumors, and asthma.

Keywords: Algorithm, Computational modeling, Gene fusion, DNA transcription.

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INTRODUCTION

The choice for the rapid method of quantifying and screening of genes, the RNA-sequencing protocol is highly employed [1-4]. It offers an advantage that it majorly does not pre-existing knowledge base for the genetic content unlike the sequencing techniques of microarray expression. Thereby, the detection of entirely novel splice variants of existing genes or that of even a completely novel gene fairly easy. But for detection of an entirely novel gene, the software employed to analyze RNA sequence must does not rely heavily on existing annotations and consequentially be capable of aligning the sequence of transcription anywhere in the genome.

In the past few studies, the algorithms by the likes of TopHat and Cufflinks are capable of ab-initio spliced alignment and previously been highly used in sequencing experiments [5,6]. Although it also has the potential of detecting of genes formed by complex of arrangements with chromosomes. However, the detecting of the matching patterns for the fusion genes remains daunting as this fusion gene formed by breakage and linkage of sets of chromosomal arrangements are the primary cause of the arise of cancers, chronic myeloid leukemia, etc., providing a host to bacteria and cancerous virus to rejoin with the vulnerable cells RNA transcription and adversely affects the cell biology [7-9].

There are over 60,000 documented cases have been reported for cancer causes from gene fusion in Mitelman database [10]. However, detecting such fusion will give an advantage of regulation and treatment of dreadful disease but it has remained an overly due task as due to the fact that in a virus affected cells the transcription cells remained the same as that of host and only fraction of it is available and responsible for alteration of transcription as in case of tumors. In addition, due to the availability of huge amount of alternative splice variants produced in a fusion event the non-transcribed promoter element will not be able to detect it. Other methods which are highly dependent on one another for preprocessing and post-processing tasks such as Bowtie, ELAND, SplitSeek, Trans-ABYSS, and BLAT depends on known annotation and for searching possible fusion boundaries uses known exons across fusion points [11-20]. To detect such fusion events, we propose the novel special-purpose algorithms from next-generation sequencers.

We demonstrate its effectiveness on six different viral and bacterial cell lines, which are populated with multiple gene fusion events, including both known and intermediary novel fusions in due process. This is a very time-consuming process and requires more than 467 CPU hours to compute assembling for 230 threads.

METHODOLOGY: TYPE MATRIX FUSION ALGORITHM (TMFA)

Given an input signal $i = (i(1), i(2), i(3), \dots, i(n))$ and the true estimation of the true signal $y = (\hat{y}(1), \hat{y}(2), \hat{y}(3), \dots)$ is given by:

$$\hat{y}(p) = \frac{1}{N} \sum_{i=0}^{N-1} i(p-1)$$

Thus, for every $p \geq N$, where N is the filter's buffer window for the number of input observation to be fused. Note that N is also the number of steps taken to detect the breaking point in the sequence of two genomes. The input dynamics of the genome sequences is given by the following function:

```
update ( ) {
  y(p+1) = φ(p)y(p)+G(p) u(p)+w(p) i(p)
  = H(p)x+v(p)
}
```

Where $\varphi(p)$ is the matrix representing the state transition, $G(p)$ is the matrix for input transition, $u(p)$ is the input vector, $H(p)$ is the measurement matrix, and u and v are the backtrack index variables for the intervals of the genomic sequences.

Algorithm: TMFA for early detection of genetic fusion.

0 Evaluate:

$$\hat{y}(p) = \frac{1}{N} \sum_{i=0}^{N-1} i(p-1)$$

update()

1. Initiate:

$$m(A_1|A_2) = \frac{\sum_{A_1 \cap A_2}^p m(\prod_{j=1}^N A_j)}{\sum_{A_1 \cap A_2}^p m(\prod_{j=1}^N A_j)}$$

Where m is the mass function, A₁ and A₂ are the two genomic sequences whereas same with B and C notations represents the subsequent fusion transcription formed in due intermediately process.

2. For each: (A₁ ⊕ A₂) do update()

3. Compute: $m(A_1|A_2) \leftarrow \sum_{A_1 \cup A_2}^p m(B_1|B_2)$

4. Check: $m(B_1|B_2) = \frac{\sum_{B_1 \cap A_2}^p m(\prod_{j=1}^N B_j)}{\sum_{A_1 \cap B_2}^p m(\prod_{j=1}^N B_j)}$

5. For each (B₁ ⊕ B₂) do update()

6. Compute: $m(B_1|B_2) \leftarrow \sum_{B_1 \cup B_2}^p m(C_1|C_2)$

7. Check: $m(C_1|C_2) = \frac{\sum_{C_1 \cap B_2}^p m(\prod_{j=1}^N C_j)}{\sum_{B_1 \cap C_2}^p m(\prod_{j=1}^N C_j)}$

8. For each (C₁ ⊕ C₂) do update()

9. Compute: $m(C_1|C_2) \leftarrow \sum_{B_1 \cup B_2}^p m(B_1|A_2)$

10. Return (p,m) transcription sequence.

11. end

12. end

13. end

14. Stop.

We have modeled the epidermal growth factor receptor (EGFR) molecules as the true signal in the above algorithm which is of prime focus for intercellular communication. As shown in Fig. 1 the two membranes with direct contact binds the receptors through EGF molecules and translate the binding into specific signals of biochemical origin within the cell. Thus, triggering migration, differentiation and cell proliferation; thereby ultimately resulting in cancer or tumor. However, if this scenario of biochemical origin persists for long, it transcribes its growth in the form of biofilms as in the case of asthma and tuberculosis. These biofilms are of emergent in nature which latter develops drug resistivity as the time passes in the similar fashion as that of the redundant RNA fusion preceded by complementary and cooperative fusion based on the interiors or intermediary RNA complexes formed from the fusion (Fig. 2). This dysfunction implicates in a variety of cancers, tumors, and another disease of DNA origin which retains its abnormal coding and influencing the health of the inherited offspring. Now, we have developed the TMFA algorithm for early detection of such transcription. Thereby, it is possible to develop and model a EGFR targeting drugs for irradiating such deadly viruses and bacteria which evolves with the host, while continuously degrading it. Till now the characteristic role of EGF is poorly understood in finding the cause of the diseases, but with TMFA we can detect in advance the potential threat to an individual with certain viruses and bacterial infection. However, this method requires long computational hours, yet it is successful enough to record and analyze the glycan chains attached to EGFR; which plays an essential role in the behavior of living cells.

CONCLUSION

Unlike the predecessor approach of discordantly mapping of known and paired reads annotations, TMFA - fusion can detect and distinguish

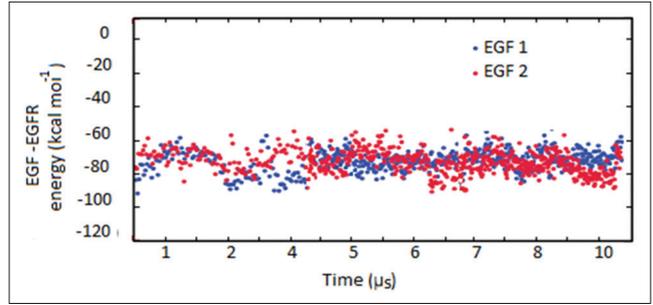


Fig. 1: Intercellular responses of two fusing RNA-sequences simulated by the type matrix fusion algorithm

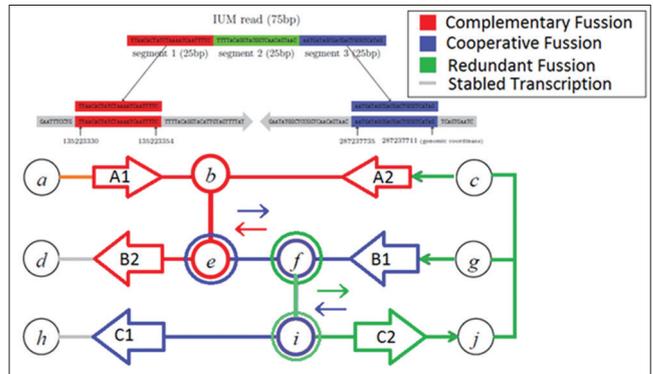


Fig. 2: Illustration of fusion types achieved from TMFA from intercellular transcription of DNA genome. Where a, d, h represents the final state whereas b, e, f, i, c, g, j are the meta states. A₁ and A₂ are the two genomic sequences whereas same with B and C notations represents the subsequent fusion transcription formed in due intermediately process

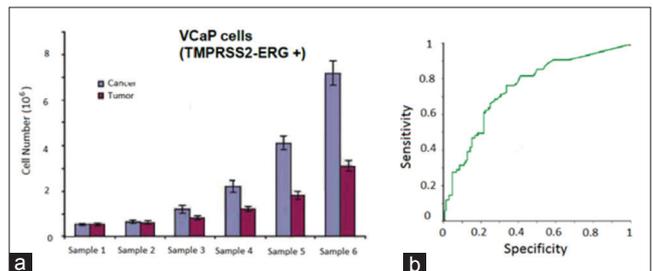


Fig. 3: (a) Sample snippet plot of six samples for the detected cancer and tumor threat from increasing number of the cell counts by the type matrix fusion algorithm (TMFA), (b) plot of the TMFA performance over 90 samples for its sensitivity versus specificity

both individual and paired reads that span gene fusions. These features increase its sensitivity and specificity (Fig. 3) and permit it to find fusions between novel genetic sequences and known splice variants. The TMFA effectively models the three logically different fusion states which are functionally the same from the perspective of its application but are required to be modeled as a single linkage for the sake of reproducing the results with high performance. Other methods might be used cooperatively with TMFA to operate in a distributed fashion. The one great challenges that remain out of the scope of this paper is to develop a big-data based population genome TMFA detection cycles to build an archive of potential threat of ever evolving viral and bacterial infection and simultaneously record its changing state or even may 1 day be successful in sequencing the transcription, i.e., virotherapy to eliminate such threats, in the near possible future.

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